

THE PML_2 LANGUAGE
INTEGRATED PROGRAM VERIFICATION IN ML

Inria

RODOLPHE LEPIGRE
GALLINETTE, NANTES – 11/12/2018

SEMANTICS AND IMPLEMENTATION OF AN EXTENSION OF ML FOR PROVING PROGRAMS



RODOLPHE LEPIGRE – 18/07/2017

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A PROGRAMMING LANGUAGE, WITH PROGRAM PROVING FEATURES

An ML-like programming language with:

- records, variants (constructors), inductive types,
- polymorphism, general recursion,
- a call-by-value evaluation strategy,
- effects (control operators),
- a light, Curry-style syntax and subtyping.

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For proving program, the type system is enriched with:

- programs as individuals (higher-order layer),
- an equality type $t \equiv u$ (observational equivalence),
- a dependent function type (typed quantification).
- Termination checking is required for proofs.

PART I SPECIFIC TYPE CONSTRUCTORS

PART II FORMALISATION OF THE SYSTEM AND SEMANTICS

PART III SEMANTICAL VALUE RESTRICTION

PART IV LOCAL SUBTYPING AND CHOICE OPERATORS

PART V CYCLIC PROOFS AND TERMINATION CHECKING

PART I

SPECIFIC TYPE CONSTRUCTORS

PROPERTIES AS PROGRAM EQUIVALENCES

Examples of (equational) program properties:

- $\text{add} (\text{add } m \ n) \ k \equiv \text{add } m \ (\text{add } n \ k)$ (associativity of add)
- $\text{rev} (\text{rev } l) \equiv l$ (rev is an involution)
- $\text{map } g \ (\text{map } f \ l) \equiv \text{map } (\text{fun } x \ \{g \ (f \ x)\}) \ l$ (map and composition)
- $\text{sort} (\text{sort } l) \equiv \text{sort } l$ (sort is idempotent)

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- $\text{sort} (\text{sort } l) \equiv \text{sort } l$ (sort is idempotent)

Specification of a sorting function using predicates:

- $\text{sorted} (\text{sort } l) \equiv \text{true}$ (sort produces a sorted list)
- $\text{permutation} (\text{sort } l) \ l \equiv \text{true}$ (sort yields a permutation)

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Remark: cannot be complete since equivalence is undecidable.

FIRST-ORDER QUANTIFICATION IS NOT ENOUGH

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type rec nat = [Zero ; S of nat]
```

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val rec add : nat  $\Rightarrow$  nat  $\Rightarrow$  nat =
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  fun n m { case n { Zero  $\rightarrow$  m | S[k]  $\rightarrow$  S[add k m] } }
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We need a form of typed quantification!

DEPENDENT FUNCTIONS FOR TYPED QUANTIFICATION

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$$\frac{\Gamma; \Xi \vdash t : \forall x \in A. B \quad \Gamma; \Xi \vdash v : A}{\Gamma; \Xi \vdash t v : B[x := v]}$$

STRUCTURING PROOFS WITH DUMMY PROGRAMS

```
val rec add_n_Sm :  $\forall n m \in \text{nat}, \text{add } n \ S[m] \equiv S[\text{add } n \ m] =$   
  fun n m {  
    case n { Zero  $\rightarrow$  {} | S[k]  $\rightarrow$  add_n_Sm k m }  
  }
```

```
val rec add_comm :  $\forall n m \in \text{nat}, \text{add } n \ m \equiv \text{add } m \ n =$   
  fun n m {  
    case n {  
      Zero  $\rightarrow$  add_n_Zero m  
      S[k]  $\rightarrow$  add_n_Sm m k; add_comm k m  
    }  
  }
```


PART II

FORMALISATION OF THE SYSTEM AND SEMANTICS

REALIZABILITY MODEL

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To construct the model, we need to:

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- 2) define the interpretation of types as sets of terms (uses reduction),
- 3) define adequate typing rules,
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Advantage: it is a very flexible approach.

CALL-BY-VALUE ABSTRACT MACHINE

Values	(Λ_v)	$v, w ::= x \mid \lambda x.t \mid \{(l_i = v_i)_{i \in I}\} \mid C_k[v]$
Terms	(Λ)	$t, u ::= v \mid t u \mid v.l_k \mid [v \mid (C_i[x_i] \rightarrow t_i)_{i \in I}] \mid \mu \alpha.t \mid [\pi]t$
Stacks	(Π)	$\pi, \xi ::= \alpha \mid \varepsilon \mid v.\pi \mid [t]\pi$ (evaluation context)
Processes		$p, q ::= t * \pi$

CALL-BY-VALUE REDUCTION RELATION

$$t \ u * \pi \succ u * [t] \pi$$

$$v * [t] \pi \succ t * v . \pi$$

$$\lambda x . t * v . \pi \succ t[x := v] * \pi$$

$$\{(l_i = v_i)_{i \in I}\} . l_k * \pi \succ v_k * \pi \quad (k \in I)$$

$$[C_k[v] \mid (C_i[x_i] \rightarrow t_i)_{i \in I}] * \pi \succ t_k[x_k := v] * \pi \quad (k \in I)$$

$$\mu \alpha . t * \pi \succ t[\alpha := \pi] * \pi$$

$$[\pi] t * \xi \succ t * \pi$$

SUCCESSFUL COMPUTATION AND OBSERVATIONAL EQUIVALENCE

The abstract machine may either:

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TYPES AS SETS OF CANONICAL VALUES

Definition: a type A is interpreted as a set of values $\llbracket A \rrbracket$ closed under (\equiv) .

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$$\llbracket \{l_1 : A_1 ; l_2 : A_2\} \rrbracket = \{ \{l_1 = v_1 ; l_2 = v_2\} \mid v_1 \in \llbracket A_1 \rrbracket \wedge v_2 \in \llbracket A_2 \rrbracket \}$$

$$\llbracket [C_1 : A_1 \mid C_2 : A_2] \rrbracket = \{ C_i[v] \mid i \in \{1, 2\} \wedge v \in \llbracket A_i \rrbracket \}$$

$$\llbracket \forall X. A \rrbracket = \bigcap_{\Phi \text{ type}} \llbracket A[X := \Phi] \rrbracket$$

$$\llbracket \exists X. A \rrbracket = \bigcup_{\Phi \text{ type}} \llbracket A[X := \Phi] \rrbracket$$

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MEMBERSHIP TYPES AND DEPENDENCY

We consider a new *membership type* $t \in A$ (with t a term, A a type).

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The dependent function type $\forall x \in A. B$

- is defined as $\forall x. (x \in A \Rightarrow B)$,
- this is a form of *relativised quantification* scheme.

SEMANTIC RESTRICTION TYPE AND EQUALITIES

We also consider a new *restriction type* $A \upharpoonright P$:

- it is build using a type A and a “semantic predicate” P ,
- $\llbracket A \upharpoonright P \rrbracket$ is equal to $\llbracket A \rrbracket$ if P is satisfied and to $\llbracket \perp \rrbracket$ otherwise.
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Remark: refinement types $\{x \in A \mid P\}$ are encoded as $\exists x.(x \in A \upharpoonright P)$.

INTERPRETATION OF THE FUNCTION TYPE

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Definition: we take $\llbracket A \Rightarrow B \rrbracket = \{\lambda x. t \mid \forall v \in \llbracket A \rrbracket, t[x := v] \in \llbracket B \rrbracket^{\perp\perp}\}$.

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$$\llbracket A \rrbracket \in \{\Phi \subseteq \Lambda_l \mid v \in \Phi \wedge v \equiv w \Rightarrow w \in \Phi\}$$

$$\llbracket A \rrbracket^{\perp} = \{\pi \in \Pi \mid \forall v \in \llbracket A \rrbracket, v * \pi \in \perp\}$$

$$\llbracket A \rrbracket^{\perp\perp} = \{t \in \Lambda \mid \forall \pi \in \llbracket A \rrbracket^{\perp}, t * \pi \in \perp\}$$

VALUE RESTRICTION AND TYPING JUDGMENTS

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$$\frac{\Gamma; \Xi \vdash t : A \Rightarrow B \quad \Gamma; \Xi \vdash u : A}{\Gamma; \Xi \vdash t u : B}$$

$$\frac{}{\Gamma, x : A; \Xi \vdash_{\text{val}} x : A}$$

$$\frac{\Gamma, x : A; \Xi \vdash t : B}{\Gamma; \Xi \vdash_{\text{val}} \lambda x. t : A \Rightarrow B}$$

ADEQUATE TYPING RULE

Theorem (adequacy lemma):

- if $\vdash t : A$ is derivable then $t \in \llbracket A \rrbracket^{\text{tt}}$,
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Proof by induction on the typing derivation.

We only need to check that our typing rules are “correct”.

For example $\frac{\vdash_{\text{val}} v : A}{\vdash v : A}$ is correct since $\llbracket A \rrbracket \subseteq \llbracket A \rrbracket^{\perp\perp}$.

ADEQUACY OF FOR ALL INTRODUCTION

$$\frac{\Gamma; \Xi \vdash_{\text{val}} v : A}{\Gamma; \Xi \vdash_{\text{val}} v : \forall X. A} \quad x \notin \Gamma$$

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We suppose $t \in \llbracket A[X := \Phi] \rrbracket^{\perp\perp}$ for all Φ , and show $t \in \llbracket \forall X.A \rrbracket^{\perp\perp}$.

However we have $\bigcap_{\Phi} \llbracket A[X := \Phi] \rrbracket^{\perp\perp} \not\subseteq \llbracket \forall X.A \rrbracket^{\perp\perp} = \left(\bigcap_{\Phi} \llbracket A[X := \Phi] \rrbracket \right)^{\perp\perp}$.

PROPERTIES OF THE SYSTEM

Theorem (normalisation):

$t : A$ implies $t * \varepsilon > v * \varepsilon$ for some value v .

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Theorem (consistency):

there is no closed term $t : \perp$.

PART III

SEMANTICAL VALUE RESTRICTION

DERIVED RULES FOR DEPENDENT FUNCTIONS

$$\frac{x : A \vdash t : B[a := x]}{\vdash_{\text{val}} \lambda x. t : \forall a \in A. B}$$

$$\frac{\vdash t : \forall a \in A. B \quad \vdash_{\text{val}} v : A}{\vdash t v : B[a := v]}$$

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Value restriction breaks the compositionality of dependent functions.

```
// add_n_Zero : ∀n∈nat, add n Zero ≡ n
```

```
add_n_Zero (add Zero S[Zero]) : add (add Zero S[Zero]) Zero ≡ add Zero S[Zero]
```

SEMANTICAL VALUE RESTRICTION

We replace $\frac{\vdash t : \forall a \in A. B \quad \vdash_{\text{val}} v : A}{\vdash t v : B[a := v]}$ by $\frac{\vdash t : \forall a \in A. B \quad \vdash u : A \quad \vdash u \equiv v}{\vdash t u : B[a := u]}$.

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The biorthogonal completion should not introduce new values.

The rule seems reasonable, but it is hard to justify semantically.

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We do not have $v \in \llbracket A \rrbracket^{\perp\perp}$ implies $v \in \llbracket A \rrbracket$ in every realizability model.

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- $w * [\lambda x. \delta_{x,v}] \varepsilon > \lambda x. \delta_{x,v} * w. \varepsilon > \delta_{w,v} * \varepsilon > w * \varepsilon \Downarrow$ if $w \in \llbracket A \rrbracket$

WELL-DEFINED CONSTRUCTION OF EQUIVALENCE AND REDUCTION

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We need to rely on a stratified construction of the two relations.

$$(\rightarrow_i) = (>) \cup \{(\delta_{v,w} * \pi, v * \pi) \mid \exists j < i, v \not\equiv_j w\}$$

$$(\equiv_i) = \{(t, u) \mid \forall j \leq i, \forall \pi, \forall \sigma, t\sigma * \pi \Downarrow_j \Leftrightarrow u\sigma * \pi \Uparrow_j\}$$

We then take

$$(\rightarrow) = \bigcup_{i \in \mathbb{N}} (\rightarrow_i) \quad \text{and} \quad (\equiv) = \bigcap_{i \in \mathbb{N}} (\equiv_i).$$

PART IV

LOCAL SUBTYPING AND CHOICE OPERATORS

A SYNTAX-DIRECTED PRESENTATION

PML₂ is hard to implement for several reasons:

- it is a Curry-style language (quantifiers are not reflected in terms),
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Solution: handle these connectives using *local subtyping*.

We then obtain a type system with:

- one typing for each term (or value) constructor,
- one typing rule for each pair of type constructors (up to commutation).

CHOICE OPERATORS AND LOCAL SUBTYPING

We replace free variables with “choice operators”:

- $\varepsilon_{x \in A}(t \notin B)$ denotes some $v \in \llbracket A \rrbracket$ such that $\llbracket t[x := a] \rrbracket \notin \llbracket B \rrbracket^{\perp\perp}$ (if possible),
- and similar things are defined for types and other syntactic elements.
- Choice operators are interpreted using elements of the semantic domain.

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We modify the system by:

- eliminating typing contexts (in favor of choice operators),
- introducing local subtyping judgments of the form $\Xi \vdash t : A \sqsubseteq B$.
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Remark: $\Xi \vdash A \subseteq B$ can be encoded as $\Xi \vdash \varepsilon_{x \in A}(x \notin B) : A \subseteq B$.

EXAMPLES OF SYNTAX-DIRECTED TYPING RULES

$$\frac{\Xi \vdash \lambda x.t : A \Rightarrow B \subseteq C \quad \Xi, \varepsilon_{x \in A}(t \notin B) \neq \square \vdash t[x := \varepsilon_{x \in A}(t \notin B)] : B}{\Xi \vdash \lambda x.t : C} \Rightarrow_i$$

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$$\frac{\Xi \vdash v : A \quad \Xi \vdash C_k[v] : [C_k : A] \subseteq B}{\Xi \vdash C_k[v] : B} +_i$$

$$\frac{\Xi \vdash v : \{l_k : A; \dots\}}{\Xi \vdash v.l_k : A} \times_e$$

EXAMPLES OF SYNTAX-DIRECTED (LOCAL) SUBTYPING RULES

$$\frac{\Xi \vdash t : A[X := C] \subseteq B}{\Xi \vdash t : \forall X. A \subseteq B} \nu_l$$

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$$\frac{\Xi \vdash t : A \subseteq B \quad \Xi \vdash t \equiv u \quad \Xi \vdash t \equiv v}{\Xi \vdash t : A \subseteq u \in B} \epsilon_r$$

EXAMPLES OF SYNTAX-DIRECTED (LOCAL) SUBTYPING RULES

$$\frac{\Xi \vdash t : A[X := C] \subseteq B}{\Xi \vdash t : \forall X. A \subseteq B} \forall_l \qquad \frac{\Xi \vdash t : A \subseteq B[X := \varepsilon_X(t \notin B)] \quad \Xi \vdash v \equiv t}{\Xi \vdash t : A \subseteq \forall X. B} \forall_r$$

$$\frac{\Xi, u_1 \equiv u_2 \vdash t : A \subseteq B \quad \Xi \vdash v \equiv t}{\Xi \vdash t : A \upharpoonright u_1 \equiv u_2 \subseteq B} \upharpoonright_l \qquad \frac{\Xi \vdash t : A \subseteq B \quad \Xi \vdash u_1 \equiv u_2}{\Xi \vdash t : A \subseteq B \upharpoonright u_1 \equiv u_2} \upharpoonright_r$$

$$\frac{\Xi, t \equiv u \vdash t : A \subseteq B \quad \Xi \vdash t \equiv v}{\Xi \vdash t : u \in A \subseteq B} \in_l \qquad \frac{\Xi \vdash t : A \subseteq B \quad \Xi \vdash t \equiv u \quad \Xi \vdash t \equiv v}{\Xi \vdash t : A \subseteq u \in B} \in_r$$

$$\frac{\Xi, w \neq \square \vdash w : A_2 \subseteq A_1 \quad \Xi, w \neq \square \vdash t w : B_1 \subseteq B_2 \quad \Xi \vdash t \equiv v}{\Xi \vdash t : A_1 \Rightarrow B_1 \subseteq A_2 \Rightarrow B_2} \Rightarrow$$

(where $w = \varepsilon_{x \in A_2}(t \ x \notin B_2)$)

PART V

CYCLIC PROOFS AND TERMINATION CHECKING

GENERAL RECURSION AND FIXPOINT UNFOLDING

Recursive programs rely on a term $\varphi a.v$ (binding a term in a value).

$$\varphi a.v * \pi \quad \rightarrow \quad v[a := \varphi a.v] * \pi \qquad \frac{\Xi \vdash v[a := \varphi a.v] : A}{\Xi \vdash \varphi a.v : A} \varphi$$

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Problem: we need to work with infinite proofs.

We introduce a cyclic structure in our proofs.

$$\frac{\forall \alpha (\Xi \vdash t : A)}{(\Xi \vdash t : A)[\alpha := \kappa]} \text{Gen} \qquad \frac{\begin{array}{c} [\forall \alpha (\Xi \vdash t : A)]^i \\ \vdots \\ (\Xi \vdash t : A)[\alpha := \varepsilon_\alpha(t \notin A)] \end{array}}{\forall \alpha (\Xi \vdash t : A)} \text{Ind}[i]$$

ORDINALS AND INDUCTIVE TYPES

$$\frac{\Xi \vdash t : A \subseteq B[X := \mu_{\infty} X.B]}{\Xi \vdash t : A \subseteq \mu_{\infty} X.B} \mu_{r,\infty}$$

ORDINALS AND INDUCTIVE TYPES

$$\frac{\Xi \vdash t : A \subseteq B[X := \mu_\infty X.B]}{\Xi \vdash t : A \subseteq \mu_\infty X.B} \mu_{\tau, \infty}$$

$$\frac{\Xi \vdash t : A \subseteq B[X := \mu_\nu X.B] \quad \Xi \vdash \nu < \tau}{\Xi \vdash t : A \subseteq \mu_\tau X.B} \mu_\tau$$

ORDINALS AND INDUCTIVE TYPES

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$$\frac{\Xi; \tau > 0 \vdash t : A[X := \mu_{\epsilon_\theta < \tau}(t \in A[X := \mu_\theta X.A])X.A] \subseteq B \quad \Xi \vdash \nu \equiv t}{\gamma; \Xi \vdash t : \mu_\tau X.A \subseteq B} \mu_\tau$$

EXAMPLE OF CYCLIC PROOF

Let us consider the “map” function: $\varphi m.\lambda f.\lambda l.[l | [] \rightarrow [] | x :: l \rightarrow f x :: m f l]$.

It can be given either of the types:

- $\forall X.\forall Y.(X \Rightarrow Y) \Rightarrow \text{List}(X) \Rightarrow \text{List}(Y)$,
- $\forall \alpha.\forall X.\forall Y.(X \Rightarrow Y) \Rightarrow \text{List}(\alpha, X) \Rightarrow \text{List}(Y)$,
- $\forall \alpha.\forall X.\forall Y.(X \Rightarrow Y) \Rightarrow \text{List}(\alpha, X) \Rightarrow \text{List}(\alpha, Y)$.

$\text{List}(\alpha, X)$ is defined as $\mu_\alpha L.[([]):\{\} | (::):X \times L]$.

CONCLUSION

FUTURE WORK

- 1) Practical issues (work in progress):
 - Composing programs that are proved terminating.
 - Extensible records and variant types (inference).
- 2) Toward a practical language:
 - Compiler using type information for optimisations.
 - Built-in types (`int64`, `float`) with their formal specification.
- 3) Theoretical questions:
 - Can we handle more side-effects? (mutable cells, arrays)
 - What can we realise with (variations of) $\delta_{v,w}$?
 - Can we extend the system with quotient types?
 - Can we formalise mathematics in the system?

Practical Subtyping for Curry-Style Languages

<https://lepigre.fr/files/publications/LepRaf2018a.pdf>

PML₂: Integrated Program Verification in ML

<https://lepigre.fr/files/publications/Lepigre2018.pdf>

Semantics and Implementation of an Extension of ML for Proving Programs

<https://lepigre.fr/files/publications/Lepigre2017PhD.pdf>

A Classical Realizability Model for a Semantical Value Restriction

<https://lepigre.fr/files/publications/Lepigre2016.pdf>

Thanks!